A Predicative Study in the Light of Angular Kinematic Variables of Body Joints during the Hop in Triple Jump

Dr. Wahid Sobhy Abd El-Ghaffar

Abstract:

The current research aims at concluding predicative equations for the performance level of triple jump in the light of some angular kinematic variables through identifying the correlation between angular kinematic variables and digital record during the hop phase in triple jump and the relative contribution of angular kinematic variables of the hop phase in digital record of triple jump in addition to concluding predicative equations for the digital record through angular kinematic variables of the hop phase in triple jump. The researcher used the descriptive (analytical) approach. The researcher purposefully chose triple jump finalists of Egypt’s Track and Field Championship (first class) 2013 (n=6). The best Three trials for each athlete were recorded and this makes (18) trials for analysis. Results indicated that indicators contributing in the digital record at the beginning of damping for first takeoff are knee angular displacement, shoulder angular displacement, hip angular acceleration, ankle angular displacement and knee angular acceleration. Indicators contributing in the digital record at the beginning of damping for second takeoff are elbow angular displacement and ankle angular acceleration. Indicators contributing in the digital record at the end of damping/ beginning of pushing for first takeoff are ankle angular velocity and knee angular displacement. Indicators contributing in the digital record at the end of damping/ beginning of pushing for second takeoff are knee angular displacement, ankle angular displacement, shoulder angular displacement and ankle angular acceleration. Indicators contributing in the digital record at the end of pushing for first takeoff are hip angular displacement, wrest angular acceleration, shoulder angular

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displacement, ankle angular velocity, wrist angular displacement, elbow angular acceleration and hip angular velocity. Indicators contributing in the digital record at the end of pushing for first takeoff are ankle angular displacement, ankle angular velocity and hip angular displacement.

Key words: Indicator – Angular Kinematic Indicators

Background:

Scientific approach is the base for reaching elite performance levels in sport. Scientific research is of major importance as it may lead to results that represent an addition to science. This importance increases as it can be used in achieving sports advances via increasing performance efficiency to higher level (6: 12, 18).


Triple Jump is a major event that is affected greatly with the advances of motor analysis for champions’ performance to identify optimum technique with the aim of improving specific learning and training programs. This is not a new trend but it has become very important recently. This indicates the importance of biomechanical analysis of triple jump. Performance levels of this event have reached impressive quantitative and qualitative levels worldwide. This is due to the use of scientific approaches in teaching and training.

Egypt is still under-represented in international and Olympic championships in this event. This indicates the importance of finding out the best ways to improve the performance level of triple
jump, in the light of modern integrated improvement of the training philosophy of athlete.

Table (1): The decreased level of Egyptian Triple Jumpers on the Arab, African, World and Olympic Levels (world record: 18.29 m)

<table>
<thead>
<tr>
<th>Championship</th>
<th>Country</th>
<th>Date</th>
<th>Place</th>
<th>Champion record</th>
<th>Number of Egyptian athletes</th>
<th>Rank</th>
</tr>
</thead>
<tbody>
<tr>
<td>African Championship for Athletics</td>
<td>Benin</td>
<td>27/6 to 1/7/2012</td>
<td>Charles Digul stadium</td>
<td>16.98m</td>
<td>1</td>
<td>7</td>
</tr>
<tr>
<td>2012 Olympic Games</td>
<td>London England</td>
<td>2-12/8/2012</td>
<td>Olympic court</td>
<td>17.81m</td>
<td>0</td>
<td>0</td>
</tr>
<tr>
<td>Arab Championship for Athletics</td>
<td>Doha Qatar</td>
<td>21-25/5/2013</td>
<td>Qatar stadium</td>
<td>17.01m</td>
<td>1</td>
<td>4</td>
</tr>
<tr>
<td>14th World Championship for Athletics</td>
<td>Moscow Russia</td>
<td>10-18/8/2013</td>
<td>Losniki court</td>
<td>‘7.20m</td>
<td>0</td>
<td>0</td>
</tr>
</tbody>
</table>

This under-representation of Egypt is due to the lack of objective science-based teaching and training programs that depend on results of biomechanical analysis for elite athletes in addition to using predictive equations through angular kinematic variables of body joints during the hop for triple jumpers.

Technique of triple jump requires that the jumper should push the floor hard with the takeoff foot then land on the same foot (during the hop). This indicates the importance of this foot according to flexion, extension and eccentric/concentric muscular work. This also indicates the importance of angular kinematics of body joints during this critical stage of movement.


Mohamed Khalil (1993) indicated that the hop is longest phase of triple jump as it represents 39% while the step represents 30% and the bounce represents 31%. Adrian & Cooper (1995) indicated that the phases of Russian triple jump are 38% for the hop, 29% for the step and 33% for the bounce. Abd El-Halim et al (2003) indicated that the optimum ratio is 37% for the hop, 29% for the step and 34% for the bounce (18: 16) (5: 320, 323) (1: 132).

This makes the hop the most important phase of triple jump as it effects the jump distance effectively. Through review of literature, the researcher did not find any previous study that relates angular kinematic variables of body joints during the hop in triple jump.

Aim:

The current research aims at concluding predicative equations for the performance level of triple jump in the light of some angular kinematic variables through:

1. Identifying the correlation between angular kinematic variables and digital record during the hop phase in triple jump
2. Identifying the relative contribution of angular kinematic variables of the hop phase in digital record of triple jump

Hypotheses:

1. There is a correlation between angular kinematic variables and digital record during the hop phase in triple jump.
2. Relative contributions of angular kinematic variables of the hop phase in digital record of triple jump vary.
3. The digital record can be predicted through angular kinematic
variables of the hop
Methods:

Approach:

The researcher used the descriptive (analytical) approach.

Participants:

The researcher chose (9) athletes purposefully. These athletes were divided into (3) athletes for the pilot study and (6) athletes (finalists of Egypt’s Athletics Championship 2013 – first class). The best (3) trials for each athlete were recorded. This makes total of (18) trials.

Tools:

The researcher used motor analysis and motor recording tools in addition to triple jump tools and some anthropometric measurements.

Pilot Study:

Motor analysis procedures:

- All athletes were equipped with markers for biomechanical analysis
- According to results of pilot study, (1) high-speed camera was fixed vertically on tripod on the left side of athletes, phase in triple jump.

Pilot study was performed on (3) athletes from the same research community and outside the main sample on 24-4-2013 at the field of the Olympic Center – Maady to identify criteria of recording performance and calibrate all tools.

Main study:

- Performance was recorded for all athletes on 25-4-2013
- DMAS7 software was used to identify the part to be analyzed (hop phase with first and second takeoff)
- Three moments were chosen for analysis (beginning of damping – end of damping/beginning of pushing – end of pushing).

10.5m away from the approach path. Height of lens from ground was 1.27m
- The camera was fixed 5.45m from the takeoff board on the half of thee hop.
- The camera was set on 120c/sec and was
attached to DMAS7 to record (live)
- Calibration device was videotaped right in the middle of movement scope and then removed
- Trials of each athlete were recorded
- Failed trials were excluded
Only the best two trials for each athlete were taken for analysis
Results:

Table (2)
### Table (3)

Predicative equations: \( Y = \text{dependent variable} - A = \text{constant} - B = \text{regression coefficient} - X = \text{independent variable} \)

1. Digital record = 4.8257 + (0.06354 x knee angular displacement) \([Y=A+BX]\)
2. Digital record = 6.1784 + (0.04957 x knee angular displacement) + (0.02112 x shoulder angular displacement) \([Y=A+B1x1+B2x2]\)
3. Digital record = 7.7985 + (0.03838 x knee angular displacement) + (0.02183 x shoulder angular displacement) + (-0.00004 x hip angular acceleration) \([Y=A+B1x1+B2x2+B3x3]\)
4. Digital record = 7.5054 + (0.06706 x knee angular displacement) + (0.00624 x shoulder angular displacement) + (-0.00006 x hip angular acceleration) + (-0.02854 x ankle angular displacement) \([Y=A+B1x1+B2x2+B3x3+B4x4]\)
5. Digital record = 8.8261 + (0.08301 x knee angular displacement) + (0.01207 x shoulder angular displacement) + (-0.00007 x hip angular acceleration) + (-0.05460 x ankle angular displacement) + (-0.00003 x knee angular acceleration) \([Y=A+B1x1+B2x2+B3x3+B4x4+B5x5]\)
Table (4)
Predicative equations: 

Digital record $= 11.6888 + (-0.0077 \times \text{Ankle angular velocity})$ $[Y=A=BX]$  

Digital record $= 19.6456 + (-0.0042 \times \text{Ankle angular velocity}) + (-0.0465 \times \text{Knee angular displacement})$ $[Y=A=B1x1+B2x2]$
Table (6)
Table (7)
Predicative equations:

1- Digital record = 3.1284 + (0.0587 x hip angular displacement) [Y=A=BX]

2- Digital record = \textbf{5.4762} + (0.0469 x hip angular displacement) + (\textbf{2.342E-05} x wrist angular acceleration) [Y=A=B1x1+B2x2]

3- Digital record = 5.9438 + (0.0376 x hip angular displacement) + (\textbf{2.200E-05} x wrist angular acceleration) + (-0.0323 x shoulder angular displacement) [Y=A=B1x1+B2x2+B3x3]

4- Digital record = 2.7681 + (0.0470 x hip angular displacement) + (\textbf{5.500E-05} x wrist angular acceleration) + (0.1013 x shoulder angular displacement) + (-\textbf{3.144E-03} x ankle angular velocity) [Y=A=B1x1+B2x2+B3x3+B4 x4]

5- Digital record = 4.0799 + (0.0574 x hip angular displacement) + (\textbf{8.840E-05} x wrist angular acceleration) + (0.1085 x shoulder angular displacement) + (-\textbf{3.999E-03} x ankle angular velocity) + (-0.0180 x wrist angular displacement) [Y=A=B1x1+B2x2+B3x3+B4 x4+B5x5]

6- Digital record = 2.871 + (0.0598 x hip angular displacement) + (\textbf{9.974E-05} x wrist angular acceleration) + (0.1181 x shoulder angular displacement) + (-0.0155 x wrist angular displacement) + (-\textbf{1.257E-05} x elbow angular acceleration) [Y=A=B1x1+B2x2+B3x3+B4 x4+B5x5+B6x6]

7- Digital record = 2.8735 + (0.0583 x hip angular displacement) + (\textbf{9.874E-05} x wrist angular acceleration) + (0.1160 x shoulder angular displacement) + (-\textbf{4.581E-03} x ankle angular velocity) + (-0.0155 x wrist angular displacement) + (-\textbf{1.257E-05} x elbow angular acceleration) + (\textbf{3.905E-07} x hip angular velocity) [Y=A=B1x1+B2x2+B3x3+B4 x4+B5x5+B6x6+B7x7]
Table (8)
Table (9)
Regression analysis of angular kinematic variables at the beginning of damping for second takeoff

<table>
<thead>
<tr>
<th>Indicators</th>
<th>Standard Error</th>
<th>Constant</th>
<th>F</th>
<th>Regression Coefficient</th>
<th>Relative contribution</th>
</tr>
</thead>
<tbody>
<tr>
<td>Elbow angular displacement</td>
<td>0.2593</td>
<td>20.991</td>
<td>125.487</td>
<td>-0.0566</td>
<td>89.20</td>
</tr>
<tr>
<td>Elbow angular displacement + ankle angular acceleration</td>
<td>0.1489</td>
<td>19.225</td>
<td>204.922</td>
<td>-0.0441</td>
<td>96.50</td>
</tr>
</tbody>
</table>

Predicative equations:

1. Digital record = 20.991 + (-0.0566 x elbow angular displacement) + (-5.341E-0 x ankle angular acceleration) [Y=A=B1x1+B2x2]
2. Digital record = 19.225 + (-0.0441 x elbow angular displacement) [Y=A=BX]
Table (10)
Table (11)
Regression analysis of angular kinematic variables at end of damping/ beginning of pushing for second takeoff

<table>
<thead>
<tr>
<th>Indicators</th>
<th>Standard Error</th>
<th>Constant</th>
<th>F</th>
<th>Regression Coefficient</th>
<th>Relative contribution</th>
</tr>
</thead>
<tbody>
<tr>
<td>Knee angular displacement</td>
<td>0.2272</td>
<td>32.3073</td>
<td>167.785</td>
<td>-0.1332</td>
<td>91.70</td>
</tr>
<tr>
<td>Knee angular displacement + ankle angular displacement</td>
<td>0.1910</td>
<td>30.2620</td>
<td>122.147</td>
<td>-0.0810 -0.0534</td>
<td>94.20</td>
</tr>
<tr>
<td>Knee angular displacement + ankle angular displacement + shoulder angular displacement</td>
<td>0.1229</td>
<td>39.5501</td>
<td>203.032</td>
<td>-0.1283 0.0698 0.1562</td>
<td>97.60</td>
</tr>
<tr>
<td>Knee angular displacement + ankle angular displacement + shoulder angular displacement + ankle angular acceleration</td>
<td>0.0814</td>
<td>39.6855</td>
<td>350.914</td>
<td>-0.1383 0.0566 0.1806 4.31E-05</td>
<td>98.90</td>
</tr>
</tbody>
</table>

Predicative equations:

1. Digital record = 32.3073 + (-0.1332 x knee angular displacement) [Y=A=B1X]
2. Digital record = 30.2620 + (-0.0810 x knee angular displacement) + (-0.0534 x ankle angular displacement) [Y=A=B1X+B2X]
3. Digital record = 39.5501 + (-0.1283 x knee angular displacement) + (-0.0698 x ankle angular displacement) + (-0.1562 x shoulder angular displacement) [Y=A=B1X+B2X+B3X+B4X]
4. Digital record = 39.6855 + (-0.1383 x knee angular displacement) + (-0.0566 x ankle angular displacement) + (-0.1806 x shoulder angular displacement) + (4.31E-05 x ankle angular acceleration) [Y=A=B1X+B2X+B3X+B4X]
Table (12)
Table (13)

Regression analysis of angular kinematic variables at end of pushing for second takeoff

<table>
<thead>
<tr>
<th>Indicators</th>
<th>Standard Error</th>
<th>Constant</th>
<th>F</th>
<th>Regression Coefficient</th>
<th>Relative contribution</th>
</tr>
</thead>
<tbody>
<tr>
<td>Ankle angular displacement</td>
<td>0.1738</td>
<td>2.9330</td>
<td>296.4931</td>
<td>0.0000</td>
<td>95.20</td>
</tr>
<tr>
<td>Ankle angular displacement + ankle angular velocity</td>
<td>0.1376</td>
<td>4.6106</td>
<td>241.3009</td>
<td>0.0873</td>
<td>97.00</td>
</tr>
<tr>
<td>Ankle angular displacement + ankle angular velocity + hip angular displacement</td>
<td>0.1117</td>
<td>5.7916</td>
<td>246.5993</td>
<td>-0.0013</td>
<td>98.00</td>
</tr>
</tbody>
</table>

Predicative equations:
1. Digital record = 2.9330 + (-0.0954 x ankle angular displacement) [Y=A=B1x1]
2. Digital record = 4.6106 + (0.0873 x ankle angular displacement) + (-9.233E-0 x ankle angular velocity) [Y=A=B1x1+B2x2]
3. Digital record = 5.7916 + (0.1163 x ankle angular displacement) + (-0.0013 x ankle angular velocity) + (-0.0232 x hip angular displacement) [Y=A=B1x1+B2x2+B3x3]

Figure (1): Dynamics of Angular displacement for the elbow, shoulder, knee and ankle during the first and second takeoff
The second important variable affecting digital record at the beginning of damping for first takeoff was shoulder angular displacement as it raised relative contribution from 90.30% to 94.80% (4.5%). This is due to the importance of arm movements during takeoff, especially at the beginning of damping, as momentum transfers from limbs to trunk. This is in agreement with Sawsan Abd El-Monem et al (1991), Talha Husam El-Din (1994) and Berequaa & Al-Sokkary (2002) (2: 156, 228) (16: 26, 27) (12: 189).
The third important variable affecting digital record at the beginning of damping for first takeoff was hip angular acceleration as it raised relative contribution from 98.80% to 97.60% (2.8%). This is due to the movement of thigh towards trunk at that portion of movement. This increases the importance of angular displacement at the beginning of the hop and therefore increasing the hip angular acceleration. This is in agreement with Sawsan Abd El-Monem et al (1991) and Ali Abd El-Rahman and Talha Husam El-Din (1994) (2: 138, 139) (3: 224).

The fourth important variable affecting digital record at the beginning of damping for first takeoff was ankle angular displacement as it raised relative contribution from 97.60% to 99.10% (1.5%). This is due to the angular change in foot and leg because of the collision of foot with takeoff board and leg turning around the horizontal axis in addition to the pushing force of takeoff till reaching the highest point of hop and the increase of hop distance without turning right or left. This is in agreement with Talha Husam El-Din (1994) and Berequaa & Al-Sokkary (2002) (15: 316, 317) (12: 51-54).

The fifth important variable affecting digital record at the beginning of damping for first takeoff was knee angular acceleration as it raised relative contribution from 99.10% to 99.40% (0.30%). Acceleration decreases as when hitting the floor at landing the decreased acceleration prepares legs to keep balance without drifting right or left. This is consistent with Bastawisy Mohamed (1997) and Osama Zaki (2006) (11: 302-303) (20: 88).

Tables (5 and 11) indicate that ankle angular velocity is the first important variable affecting digital record at the end of damping/beginning of push for first takeoff with relative contribution of 88.10%. During the end of damping/beginning of push for second takeoff (table 11), ankle angular displacement raised relative contribution from 91.70% to 94.20% (2.5%) while ankle angular acceleration raised relative contribution from 97.60% to 98.90% (1.3%). This is because of the angular change in foot and leg due to the movement quickness especially at the ankle at the beginning of pushing. This produced angular displacement and angular velocity at the ankle. Angular acceleration increases with the increase of angular velocity. This is consistent with Bridgett (2002), Talha Husam El-Din (1993) and Berequaa & Al-Sokkary (2002) (13: 80-84) (15: 316-317) (12: 51-54).
Tables (5 and 11) indicate that knee angular displacement is the second important variable affecting digital record at the end of damping/beginning of push for first takeoff as raised relative contribution from 88.10% to 92.30% (4.2%). For the same variable at the second takeoff, relative contribution was 91.70%. This is because of the important role of knee extensors at the beginning of the push as triple jumpers need horizontal displacement more than vertical displacement with consistent rhythm. This is consistent with Bastawisy Mohamed (1997) and Susan Hall (2000) (11: 292) (19: 364).

Tables (7 and 13) indicate that hip angular displacement is the first important variable affecting digital record at the end of push for first takeoff with relative contribution of 84%. At second takeoff, the same variable raised relative contribution from 97% to 98% (1%). This is due to the extension of thigh and pushing the floor hard with full use of leg joints’ range of motion at the end of pushing. This increases the importance of hip angular displacement. This is consistent with Sawsan Abd El-Monem et al (1991), Talha Husam El-Din (1994) and Berequaa & Al-Sokkary (2002) (2: 156, 228) (16: 26, 27) (12: 189).

Table (7) indicate that wrist angular acceleration is the second important variable affecting digital record at the end of push for first takeoff as raised relative contribution from 84% to 88.10% (4.1%). Shoulder angular displacement is the third important variable affecting digital record at the end of push for first takeoff as raised relative contribution from 88.10% to 91% (2.9%). This is due to the importance of arm velocity, especially at the shoulder and wrist joints. This produces angular displacements for these two joints. The increase of wrist angular displacement led to increasing the angular velocity and angular acceleration at the end of pushing as momentum is transferred from limbs to trunk. This is consistent with Sawsan Abd El-Monem et al (1991), Talha Husam El-Din (1994) and Berequaa & Al-Sokkary (2002) (2: 156, 228) (16: 26, 27) (12: 189).

Tables (7 and 13) indicate that ankle angular velocity is the fourth important variable affecting digital record at the end of push for first takeoff as raised relative contribution from 91% to 95.90% (4.9%). As for the second takeoff ankle angular displacement came first with relative contribution of 95.20% while ankle angular velocity came second as it raised relative...
contribution from 95.20% to 97% (1.8%). This is because of the angular change in foot and leg due to the movement quickness especially at the ankle at the end of pushing with the increase of hop distance and consequently bounce distance without any deviation to right or left. This is consistent with Bridgett (2002), Talha Husam El-Din (1993) and Berequaa & Al-Sokkary (2002) (13: 80-84) (15: 316-317) (12: 51-54).

Table (7) indicate that wrist angular displacement is the fifth important variable affecting digital record at the end of push for first takeoff as raised relative contribution from 95.90% to 99.60% (3.7%) while the sixth variable is elbow angular acceleration as it raised relative contribution from 99.60% to 99.80% (0.20%). This is due to the importance of arm and wrist quickness which produces wrist and elbow angular displacement. This increased the angular velocity and angular acceleration of elbow at the end of pushing while momentum is transferred from limbs to trunk. This is consistent with Sawsan Abd El-Monem et al (1991), Talha Husam El-Din (1994) and Berequaa & Al-Sokkary (2002) (2: 156, 228) (16: 26, 27) (12: 189).

Table (7) indicate that hip angular velocity is the seventh important variable affecting digital record at the end of push for first takeoff as raised relative contribution from 99.80% to 100% (1.2%). This is due to extension of thigh joint, pushing the floor hard and using full extension of leg joints at the end of pushing. This increases hip angular displacement and angular velocity. This is consistent with Sawsan Abd El-Monem et al (1991) and Ali Abd El-Rahman and Talha Husam El-Din (1994) (2: 138-139) (3: 224).

Table (9) indicated that elbow angular displacement is the first important variable affecting digital record at the beginning of damping for second takeoff with relative contribution of 89.20%. this is due to the importance of arm movement producing elbow angular displacement while momentum transfers from limbs to trunk. This is consistent with Sawsan Abd El-Monem et al (1991), Talha Husam El-Din (1994) and Berequaa & Al-Sokkary (2002) (2: 156, 228) (16: 26, 27) (12: 189).

Table (9) also indicate that ankle angular acceleration is the second important variable affecting digital record at the beginning of damping for second takeoff as raised relative contribution from 89.20% to 96.50% (7.3%). This is because of the angular change in foot and leg due to the movement quickness.
especially at the ankle at the beginning of damping where angular velocity, and consequently angular acceleration, increases. This is consistent with Talha Husam El-Din (1993) and Berequaa & Al-Sokkary (2002) (15: 316-317) (12: 51-54).

Table (11) indicate that shoulder angular displacement is the third important variable affecting digital record at the end of damping/beginning of push for second takeoff as raised relative contribution from 94.20% to 97.60% (3.4%). This is due to the importance of arm movement, especially at the shoulder joint. This produces angular displacement at the beginning of pushing with momentum transferring from limbs to trunk. This is consistent with Sawsan Abd El-Monem et al (1991), Talha Husam El-Din (1994) and Berequaa & Al-Sokkary (2002) (2: 156, 228) (16: 26, 27) (12: 189).

Conclusions:

According to these results, the researcher concluded the following:

A. Indicators contributing in the digital record at the beginning of damping for first takeoff are knee angular displacement, shoulder angular displacement, hip angular acceleration, ankle angular displacement and knee angular acceleration.

Predicative equations:

\( Y = \text{dependent variable} - A = \text{constant} - B = \text{regression coefficient} - X = \text{independent variable} \)

6. Digital record = 4.8257 + (0.06354 x knee angular displacement) \([Y=A+BX]\)

7. Digital record = 6.1784 + (0.04957 x knee angular displacement) + (0.02112 x shoulder angular displacement) \([Y=A+B1x1+B2x2]\)

8. Digital record = 7.7985 + (0.03838 x knee angular displacement) + (0.02183 x shoulder angular displacement) + (-0.00004 x hip angular acceleration) \([Y=A+B1x1+B2x2+B3x3]\)

9. Digital record = 7.5054 + (0.06706 x knee angular displacement) + (0.00624 x shoulder angular displacement) + (-0.00006 x hip angular acceleration) + (-0.02854 x ankle angular displacement) \([Y=A+B1x1+B2x2+B3x3+B4x4]\)

10. Digital record = 8.8261 + (0.08301 x knee angular displacement) + (0.01207 x shoulder angular displacement) + (-0.00007 x hip angular acceleration) + (-0.05460 x ankle angular displacement + (-0.00003 x knee angular acceleration) \([Y=A+B1x1+B2x2+B3x3+B4x4+B5x5]\)

B. Indicators contributing in the digital record at the beginning of damping for second takeoff are
elbow angular displacement and ankle angular acceleration.

**Predicative equations:**
3. Digital record = 20.991 + (-0.0566 x elbow angular displacement) [Y=A=BX]
4. Digital record = 19.225 + (-0.0441 x elbow angular displacement) + (-5.341E-0 x ankle angular acceleration) [Y=A=B1x1+B2x2]

C. Indicators contributing in the digital record at the end of damping/beginning of pushing for **first takeoff** are ankle angular velocity and knee angular displacement.

**Predicative equations:**
1. Digital record = 11.6888 + (-0.0077 x ankle angular velocity) [Y=A=BX]
2. Digital record = 19.6456 + (-0.0042 x ankle angular velocity) + (-0.0465 x knee angular displacement) [Y=A=B1x1+B2x2]

D. Indicators contributing in the digital record at the end of damping/beginning of pushing for **second takeoff** are knee angular displacement, ankle angular displacement, shoulder angular displacement and ankle angular acceleration.

**Predicative equations:**
5. Digital record = 32.3073 + (-0.1332 x knee angular displacement) [Y=A=BX]
6. Digital record = 30.2620 + (-0.0810 x knee angular displacement) + (-0.0534 x ankle angular displacement) [Y=A=B1x1+B2x2]
7. Digital record = 39.5501 + (-0.1283 x knee angular displacement) + (-0.0698 x ankle angular displacement) + (-0.1562 x shoulder angular displacement) [Y=A=B1x1+B2x2+B3x3]
8. Digital record = 39.6855 + (-0.1383 x knee angular displacement) + (-0.0566 x ankle angular displacement) + (-0.1806 x shoulder angular displacement) + (4.31E-05 x ankle angular acceleration) [Y=A=B1x1+B2x2+B3x3+B4x4]

E. Indicators contributing in the digital record at the end of pushing for **first takeoff** are hip angular displacement, wrist angular acceleration, shoulder angular displacement, ankle angular velocity, wrist angular displacement, elbow angular acceleration and hip angular velocity.

**Predicative equations:**
8- Digital record = 3.1284 + (0.0587 x hip angular displacement) [Y=A=BX]
9- Digital record = 5.4762 + (0.0469 x hip angular displacement) + (2.342E-05 x wrist angular acceleration) [Y=A=B1x1+B2x2]
10- Digital record = 5.9438 + (0.0376 x hip angular displacement) + (2.200E-05 x wrist angular acceleration)
acceleration) + (-0.0323 x shoulder angular displacement)

\[ Y = A = B_1 x_1 + B_2 x_2 + B_3 x_3 \]

11- Digital record = 2.7681 + (0.0470 x hip angular displacement) + (5.500E-05 x wrist angular acceleration) + (0.1013 x shoulder angular displacement) + (-3.144E-03 x ankle angular velocity)

\[ Y = A = B_1 x_1 + B_2 x_2 + B_3 x_3 + B_4 x_4 \]

12- Digital record = 4.0799 + (0.0574 x hip angular displacement) + (8.840E-05 x wrist angular acceleration) + (0.1085 x shoulder angular displacement) + (-3.999E-03 x ankle angular velocity) + (-0.0180 x wrist angular displacement)

\[ Y = A = B_1 x_1 + B_2 x_2 + B_3 x_3 + B_4 x_4 + B_5 x_5 \]

13- Digital record = 2.871 + (0.0598 x hip angular displacement) + (9.974E-05 x wrist angular acceleration) + (0.1181 x shoulder angular displacement) + (-4.584E-03 x ankle angular velocity) + (-0.0155 x wrist angular displacement) + (1.257E-05 x elbow angular acceleration)

\[ Y = A = B_1 x_1 + B_2 x_2 + B_3 x_3 + B_4 x_4 + B_5 x_5 + B_6 x_6 \]

14- Digital record = 2.8735 + (0.0583 x hip angular displacement) + (9.874E-05 x wrist angular acceleration) + (0.1160 x shoulder angular displacement) + (-4.581E-03 x ankle angular velocity) + (-0.0155 x wrist angular displacement) + (1.257E-05 x elbow angular acceleration) + (3.905E-07 x hip angular velocity)

\[ Y = A = B_1 x_1 + B_2 x_2 + B_3 x_3 + B_4 x_4 + B_5 x_5 + B_6 x_6 + B_7 x_7 \]

F. Indicators contributing in the digital record at the end of pushing for Second takeoff are ankle angular displacement, ankle angular velocity and hip angular displacement.

Predicative equations:

4. Digital record = 2.9330 + (-0.0954 x ankle angular displacement)

\[ Y = A = B_1 x_1 + B_2 x_2 + B_3 x_3 + B_4 x_4 + B_5 x_5 \]

5. Digital record = 4.6106 + (0.0873 x ankle angular displacement) + (-9.233E-0 x ankle angular velocity) + (-4.584E-03 x ankle angular displacement) + (-3.999E-03 x ankle angular velocity) + (-0.0155 x ankle angular velocity)

\[ Y = A = B_1 x_1 + B_2 x_2 + B_3 x_3 + B_4 x_4 + B_5 x_5 \]

6. Digital record = 5.7916 + (0.1163 x ankle angular displacement) + (-0.0013 x ankle angular velocity) + (-0.0232 x hip angular displacement)

\[ Y = A = B_1 x_1 + B_2 x_2 + B_3 x_3 + B_4 x_4 + B_5 x_5 + B_6 x_6 + B_7 x_7 \]

Recommendations:

In the light of these conclusions, the researcher recommends that:

1- Indicators under investigation that proved to be affecting the digital record of triple jump should be used, along with its predicative equations, in selecting triple jumpers

2- Training programs for the hop stage of triple jump should be designed in the light of these indicators and predicative equations.
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